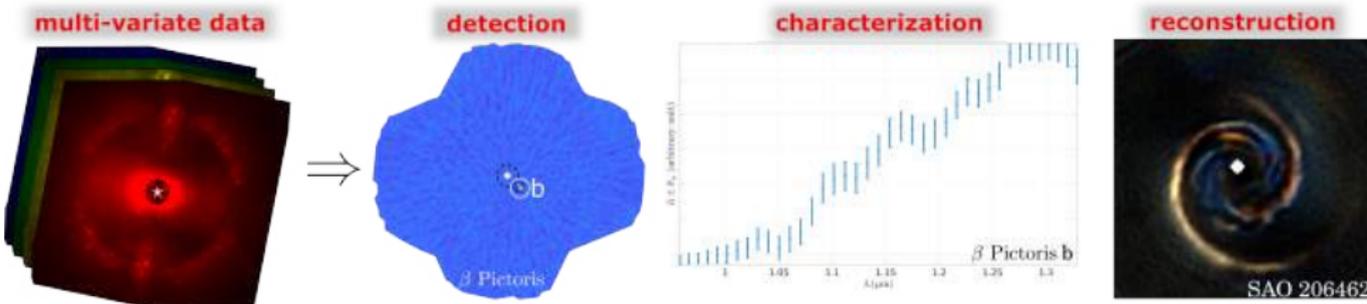


# Approches *science des données* pour l'exploration des environnements circumstellaires en imagerie à haut contraste & haute résolution angulaire

Olivier Flasseur



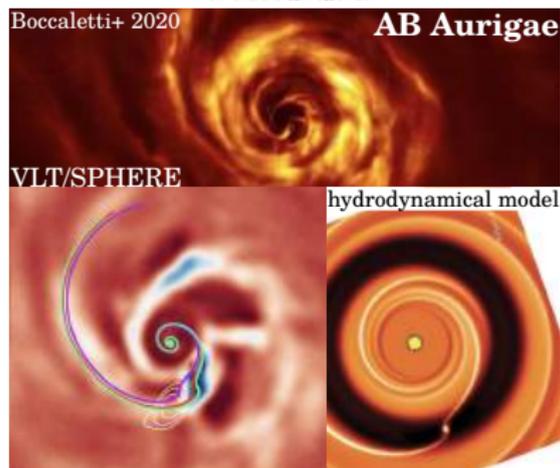
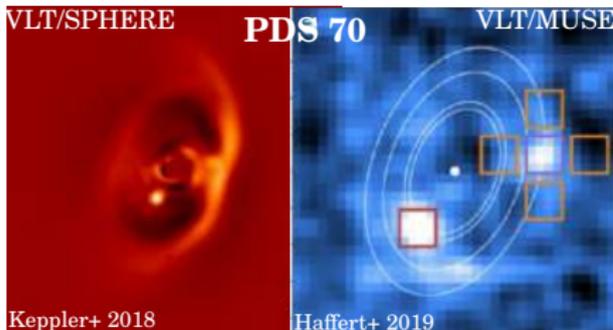
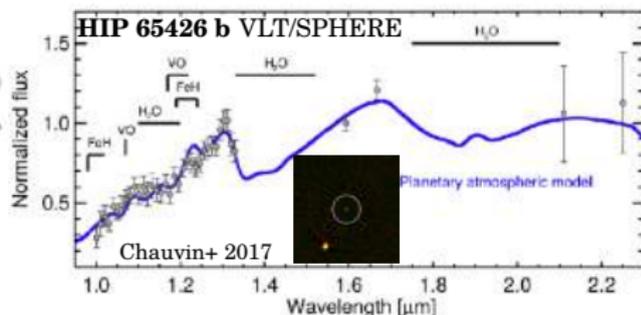
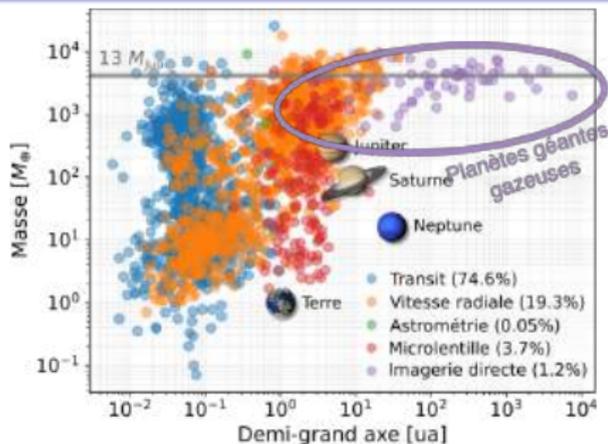
travaux conjoints avec de nombreux collègues et étudiants, notamment du :



Journées  - 04 au 07 juin 2024 - Marseille



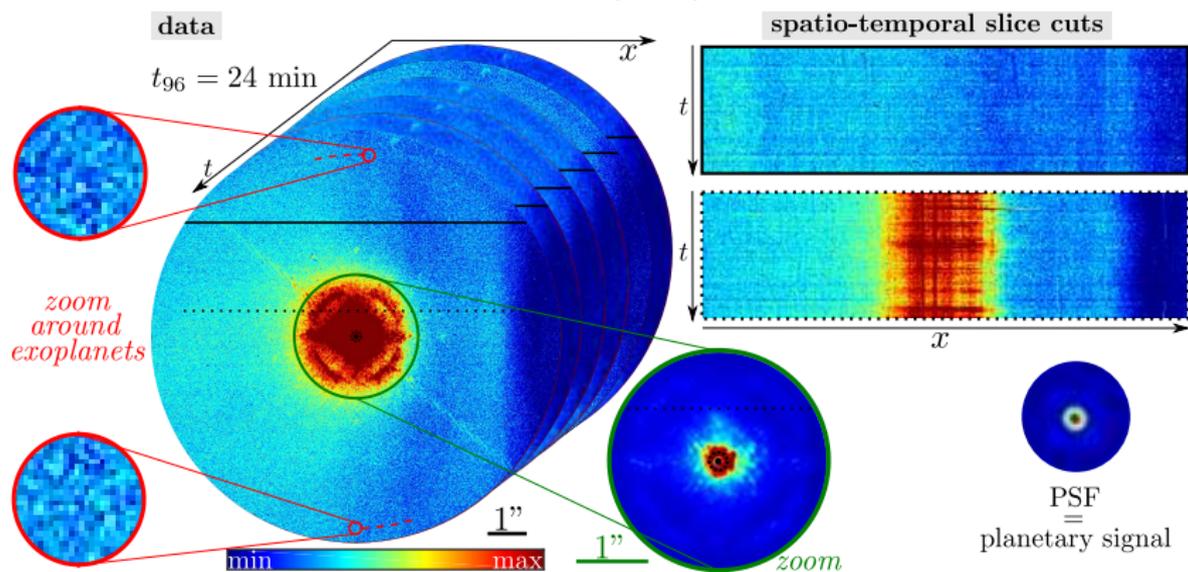
# Exoplanetary science – some key scientific drivers



**Frequency and diversity of planets? Architecture of systems?  
How do planets form? How do planets interact with the disk?**

# Goal: modeling the nuisance component (speckles + noise)

## angular differential imaging (ADI) = temporal diversity



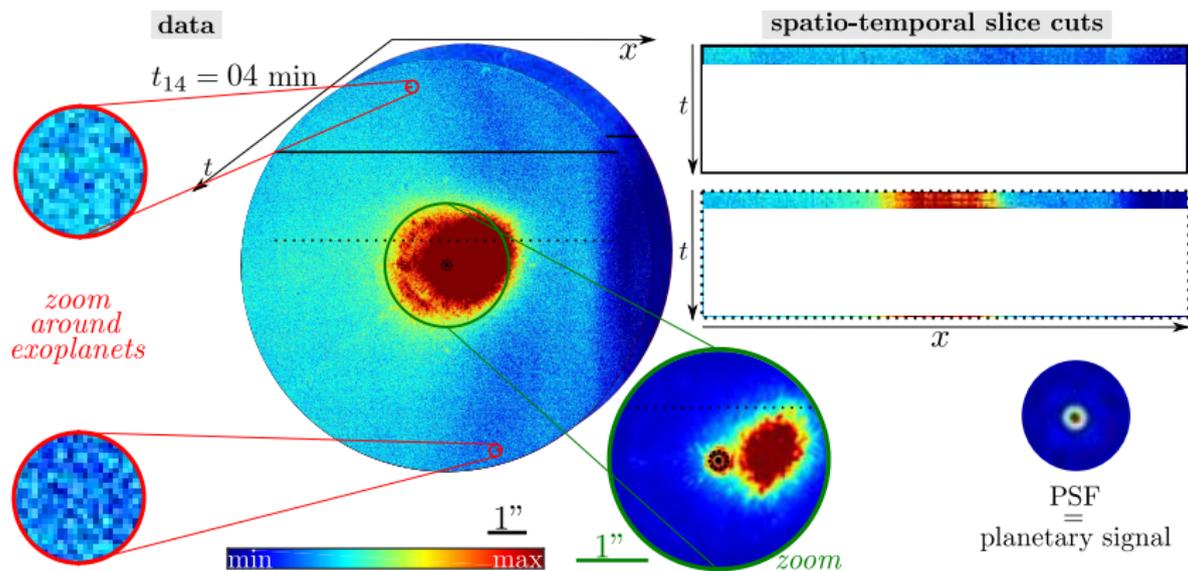
### Peculiarities

- **Faint signal** from the exoplanets
- **Non-stationary** and **spatially correlated** strong nuisance component
- **Strong fluctuations** (stellar leakages)
- **Multi-spectral** data available

⇒ **Signal unmixing is critical**

# Goal: modeling the nuisance component (speckles + noise)

## angular differential imaging (ADI) = temporal diversity



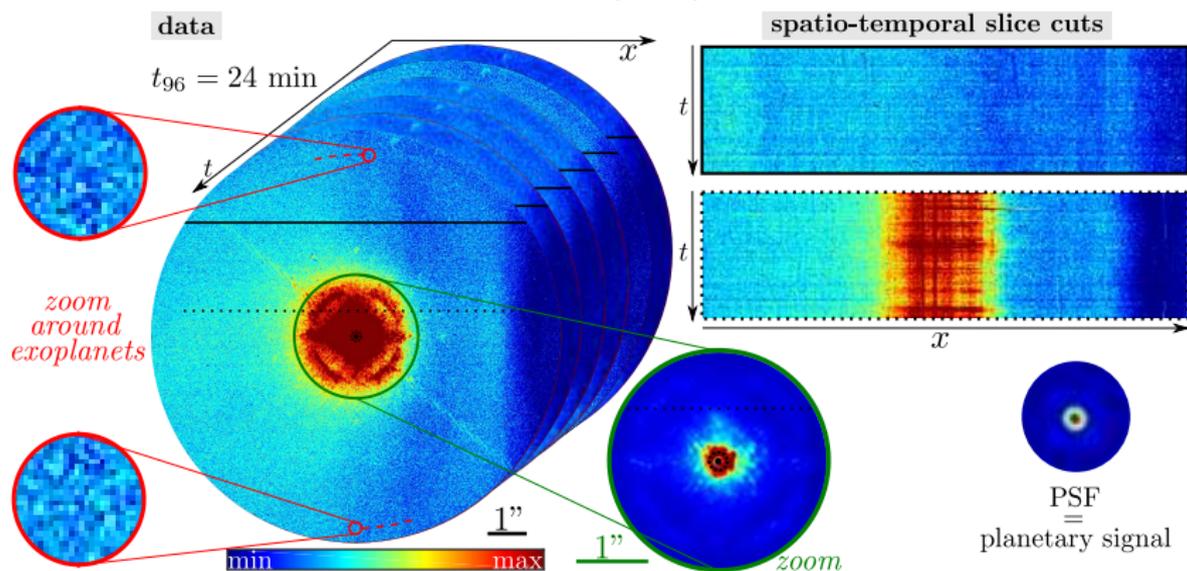
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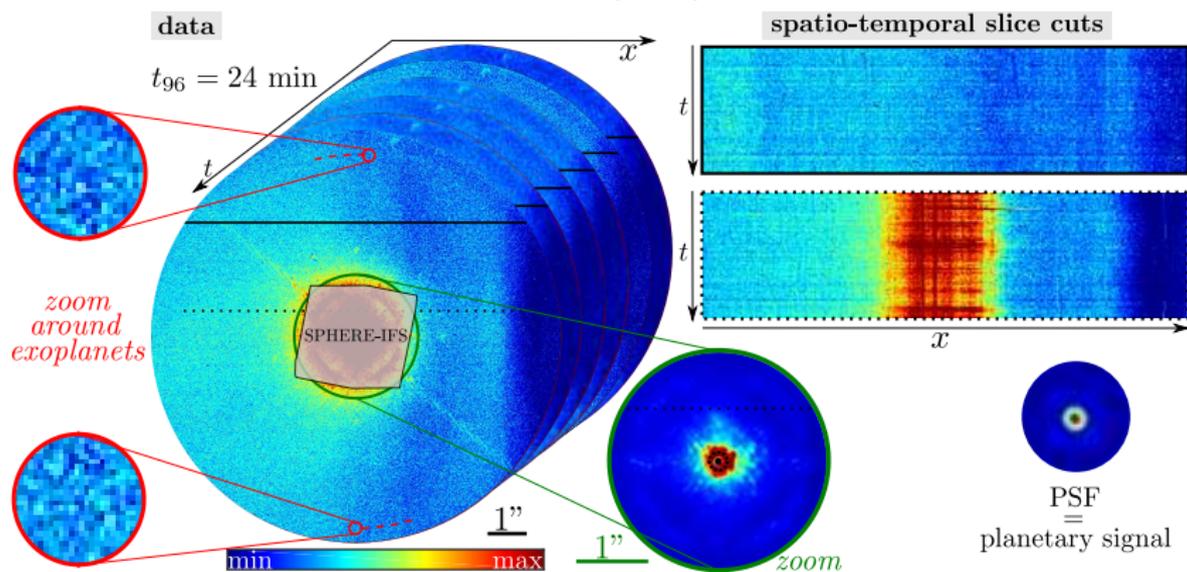
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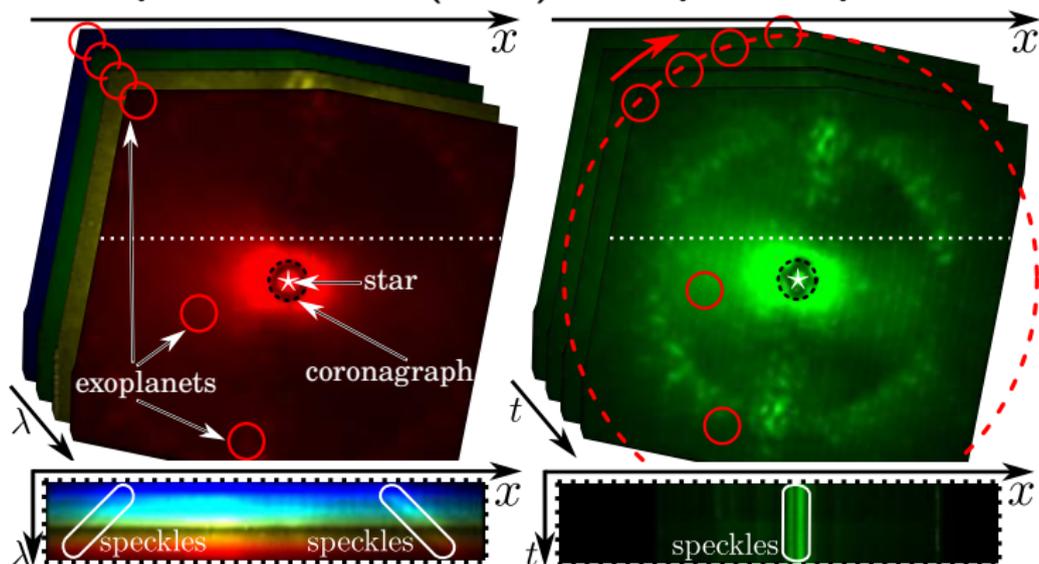
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⇒ **Signal unmixing is critical**

# Goal: modeling the nuisance component (speckles + noise)

angular & spectral diff. im. (ASDI) = temporal & spectral diversity



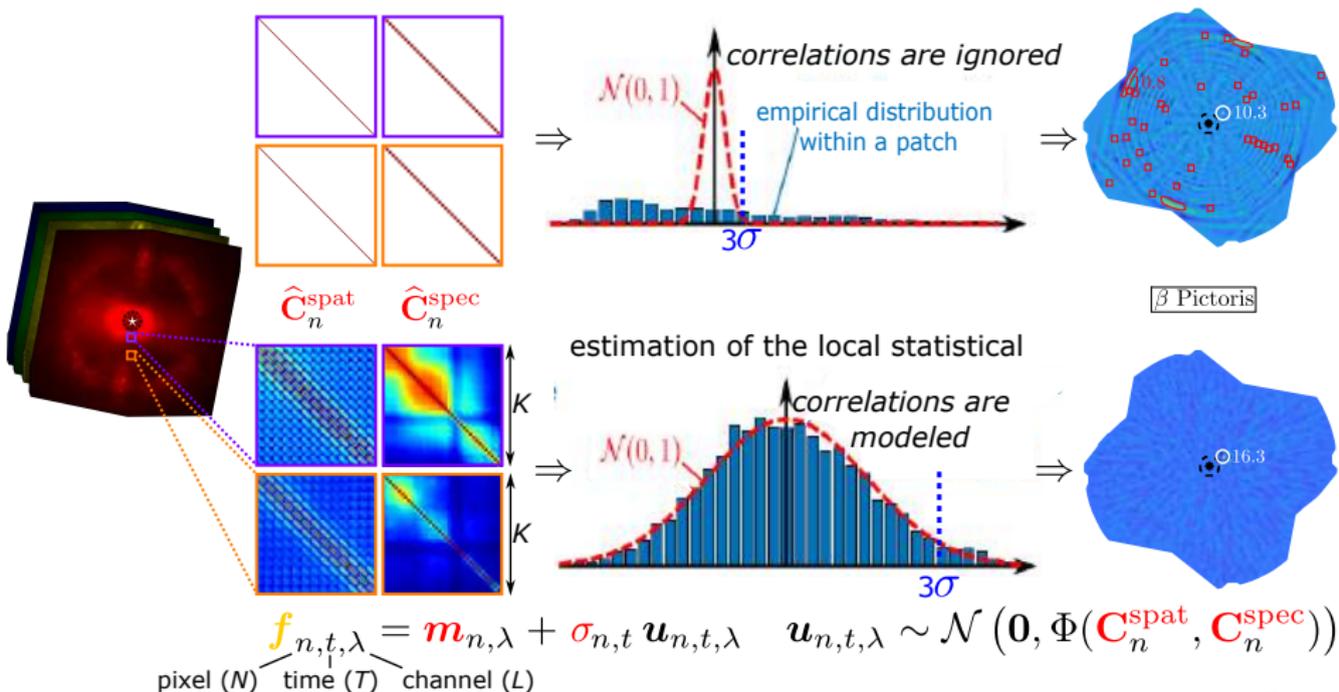
## Peculiarities

- **Faint signal** from the exoplanets
- **Non-stationary** and **spatially correlated** strong nuisance component
- **Strong fluctuations** (stellar leakages)
- **Multi-spectral** data available

⇒ **Signal unmixing is critical**

# Accounting for the *correlations* of the nuisance component

## standard processing pipeline

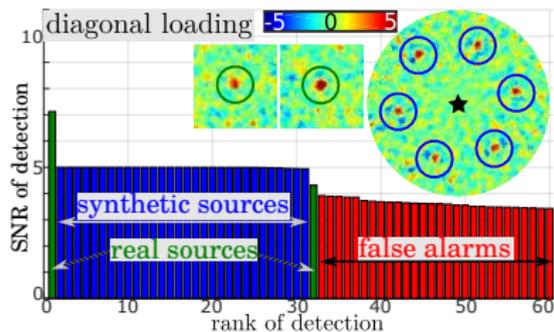
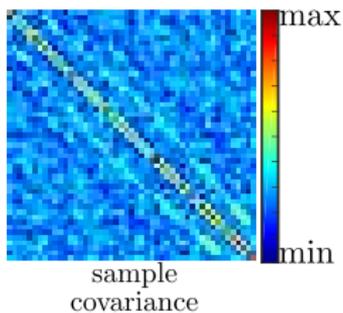


## beyond white noise hypothesis

⇒ unsupervised and regularized estimation from the data

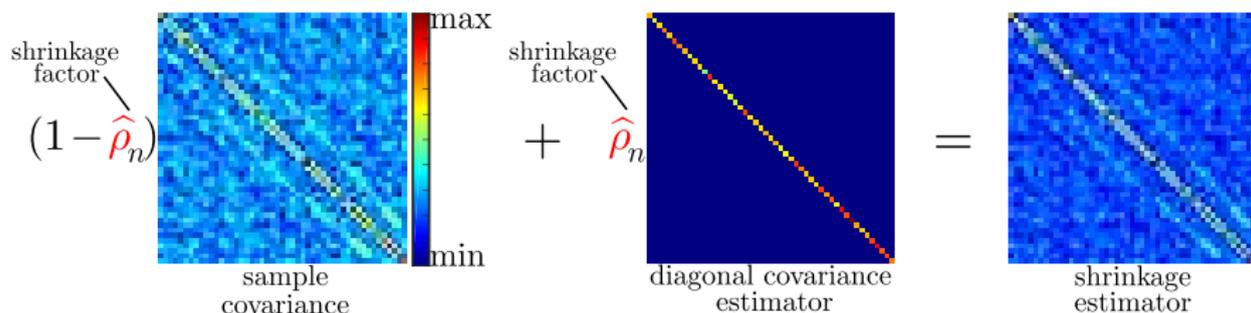
# Accurate estimation in large dimension – *example*

- Low nb of samples  $\Rightarrow$  empirical covariances very noisy / rank deficient

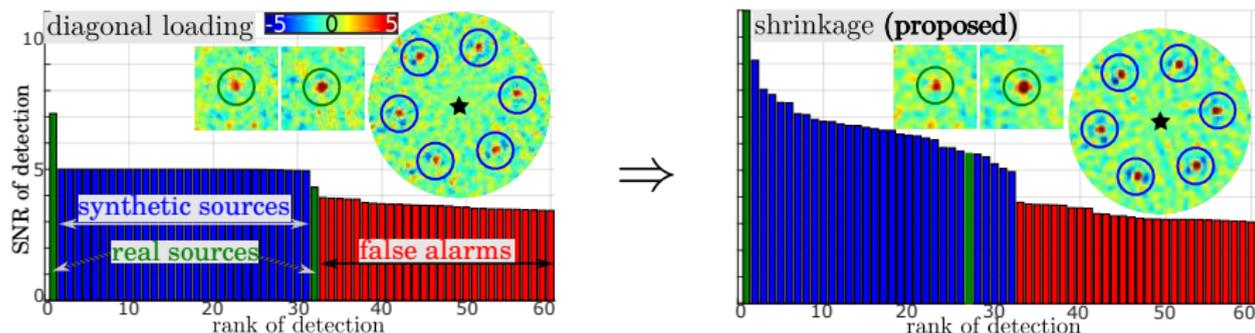


# Accurate estimation in large dimension – *example*

- Low nb of samples  $\Rightarrow$  empirical covariances very noisy / rank deficient
- Data-driven and spatially adaptive regularization by *shrinkage*:

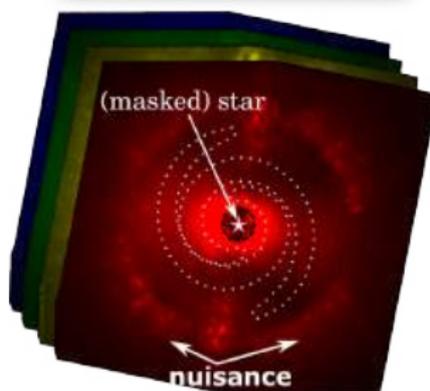


$\Rightarrow$  **optimal estimation by risk minimization for various structures**



# Data science: essential for high-contrast imaging

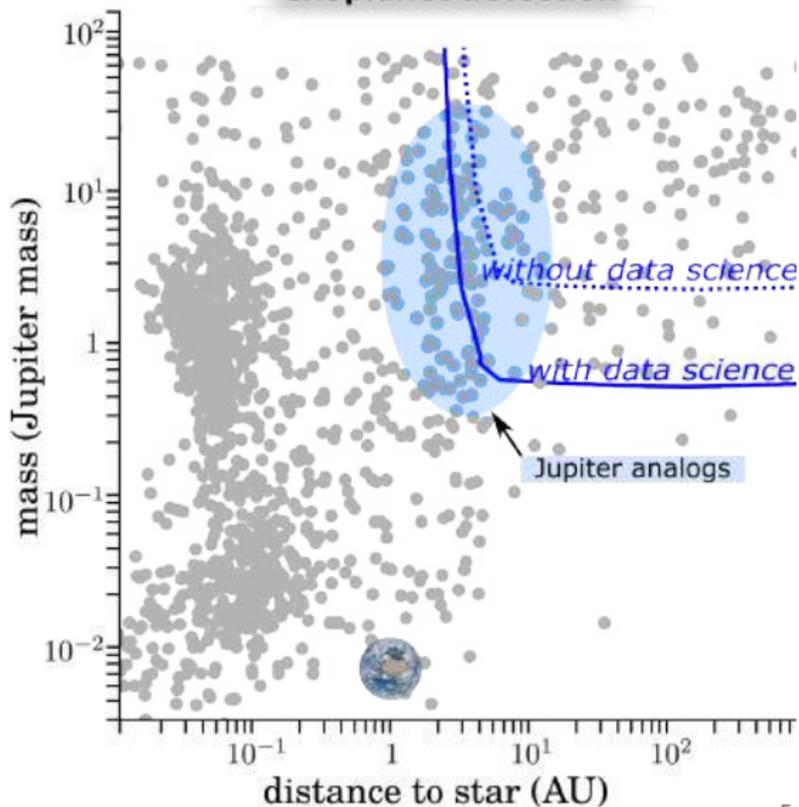
## disk reconstruction



↓ data science ↓

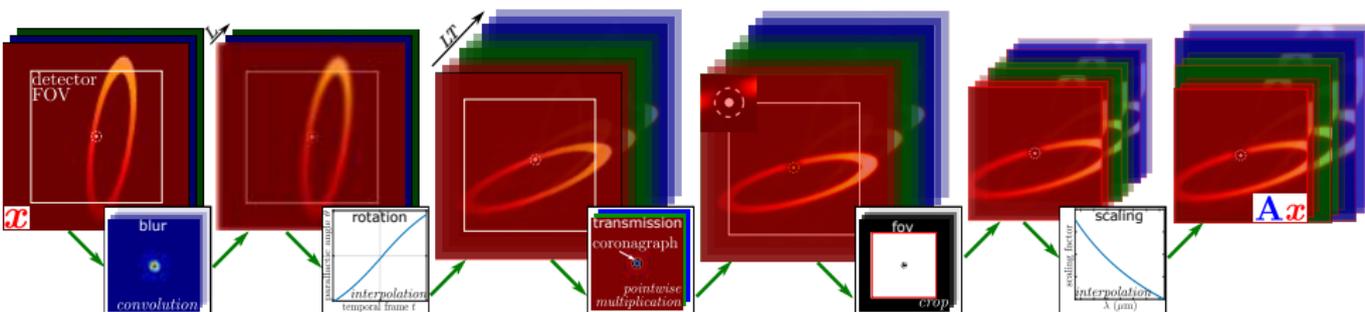


## exoplanet detection



# Regularized reconstruction – framework

- Data model:  $\mathbf{r} = \mathbf{A} \mathbf{x} + \mathbf{f} \in \mathbb{R}^{NLT}$  with  $\mathbf{x} \in \mathbb{R}^{N'L}$ ,  $\mathbf{f} \gg \mathbf{A} \mathbf{x}$ .
- Direct operator:  $\mathbf{A} \equiv \text{scaling} \circ \text{fov} \circ \text{transmission} \circ \text{rotation} \circ \text{blur}$ .



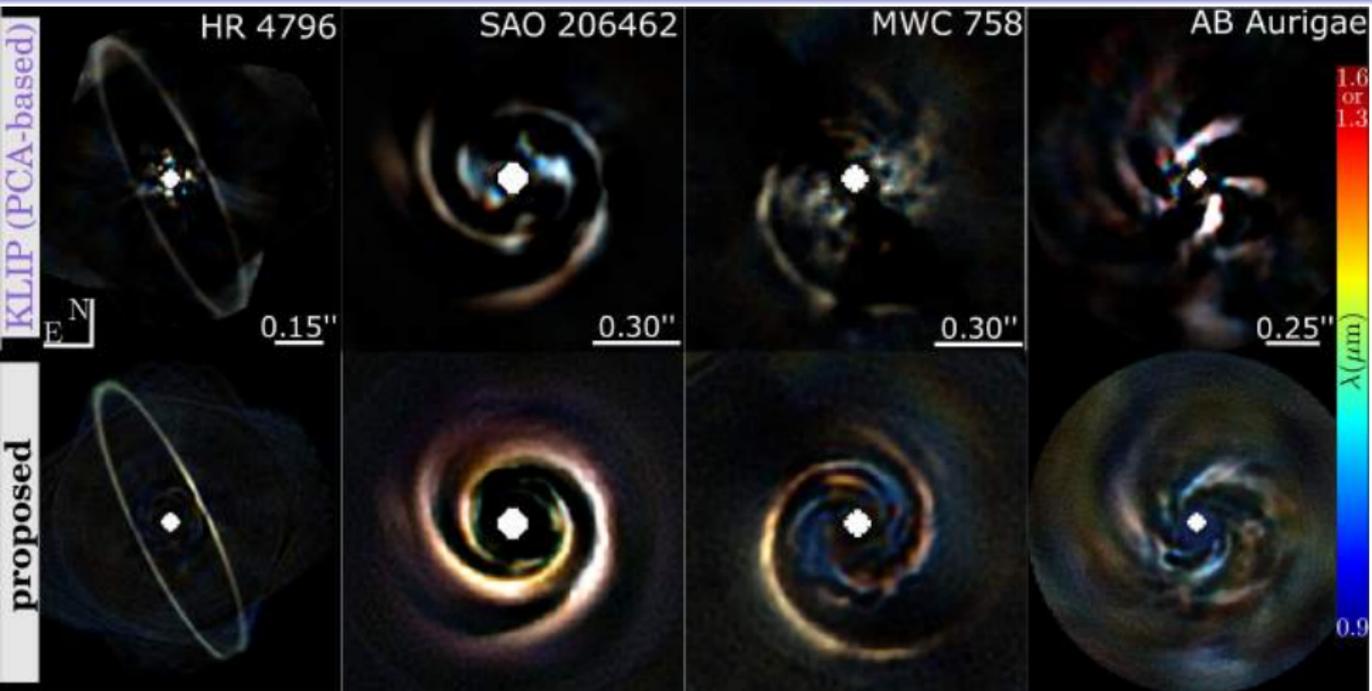
## Regularized reconstruction of the spatio-spectral flux distribution $\mathbf{x}$

Solving an inverse-problem:

$$\hat{\mathbf{x}} = \arg \min_{\mathbf{x} > 0} \{ \mathcal{L}(\mathbf{r}, \mathbf{x}, \mathbf{A}, \boldsymbol{\Omega}, \boldsymbol{\mu}) = \mathcal{D}(\mathbf{r}, \mathbf{A} \mathbf{x}, \boldsymbol{\Omega}) + \mathcal{R}(\mathbf{x}, \boldsymbol{\mu}) \},$$

- $\mathcal{D}(\mathbf{r}, \mathbf{A} \mathbf{x}, \boldsymbol{\Omega})$ : data-fidelity term, depends on  $\boldsymbol{\Omega}$  statistics of  $\mathbf{f}$ ,
- $\mathcal{R}(\mathbf{x}, \boldsymbol{\mu})$ : regularization term, depends on hyperparameters  $\boldsymbol{\mu}$ .

# Results: *disk reconstruction from SPHERE-IFS data*



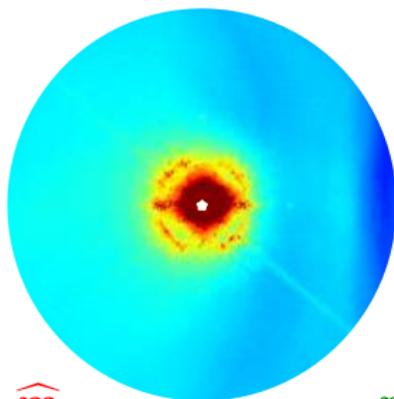
*statistical model*  $\Rightarrow$  reduced residual stellar leakages

*image formation model*  $\Rightarrow$  reduced artifacts & improved resolution

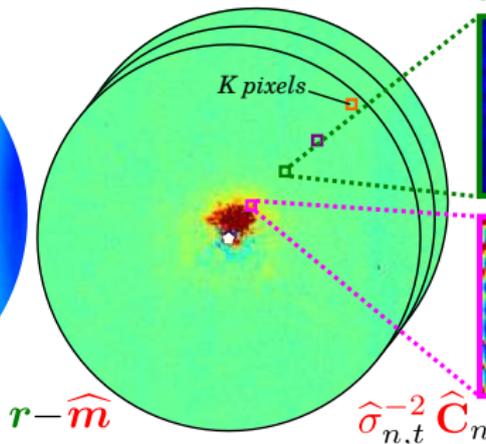
**Joint spectral processing**  $\Rightarrow$  **critical for complex disk structures**

# Statistical modeling: *removing (most of) the correlations*

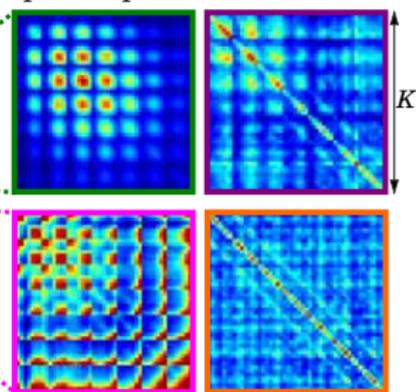
temporal mean



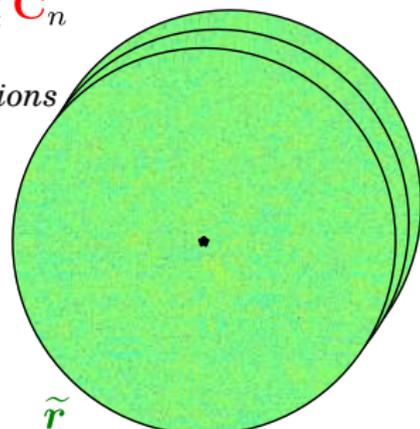
centered observations



spatial patch covariances



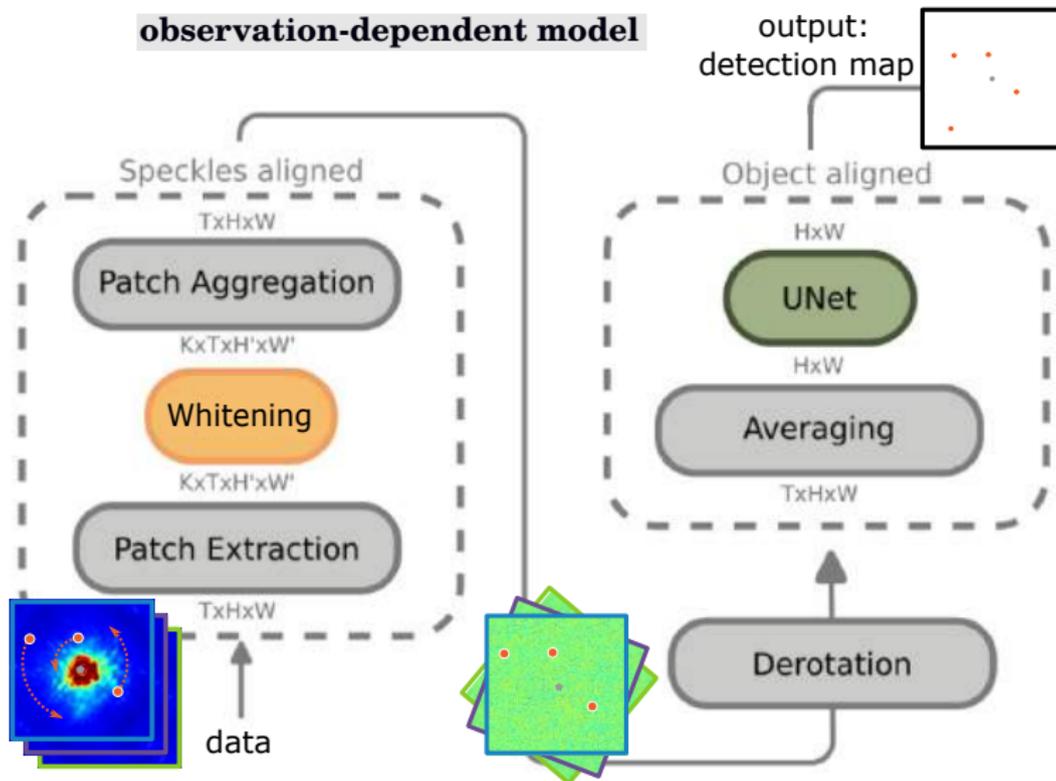
centered &amp; whitened observations



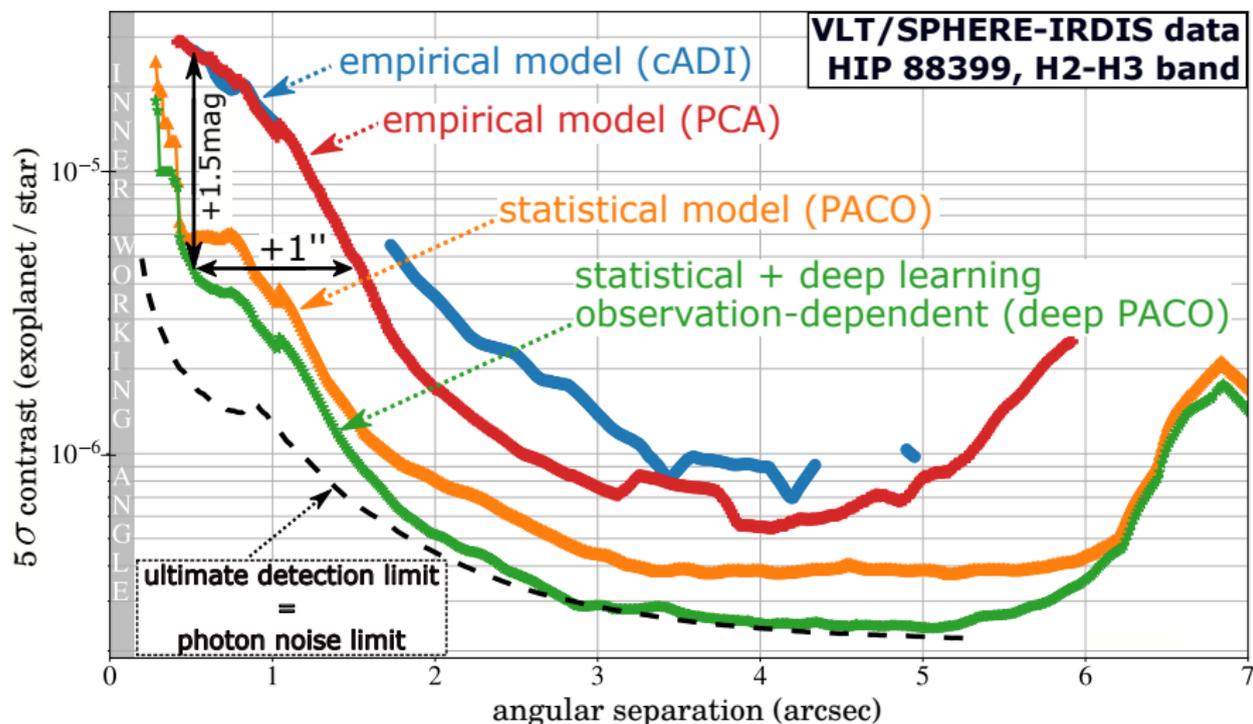
⇒ **Contrast and stationarity are improved**

⇒ **Residual structures / noise will be captured by deep learning**

# Deep learning: *capturing residual correlations*



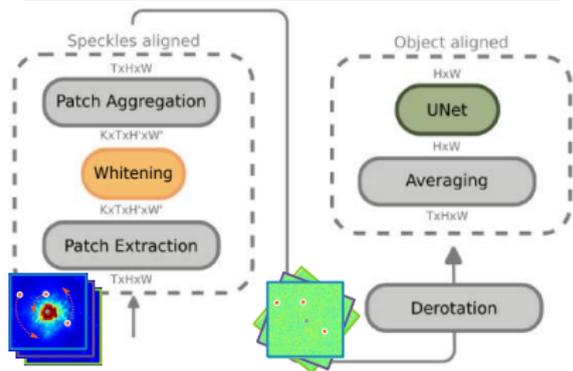
# Results: improved detection sensitivity



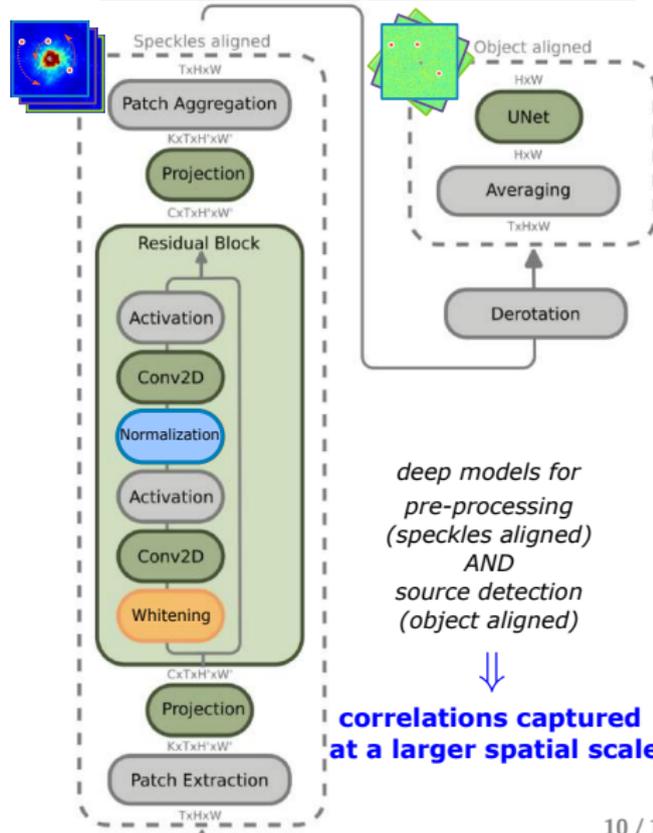
**statistics + deep learning  $\Rightarrow$  gain & optimal far from the star**

# Deep learning: *capturing residual correlations*

## observation-dependent model (1)



## observation-independent model (2)



Common part: **whitening**  
via estimation of spatial covariances

### Outputs

model (1): binary detection map



model (2): residual flux distribution cube



reconstruction loss (flux)  
instead of detection loss

improved robustness

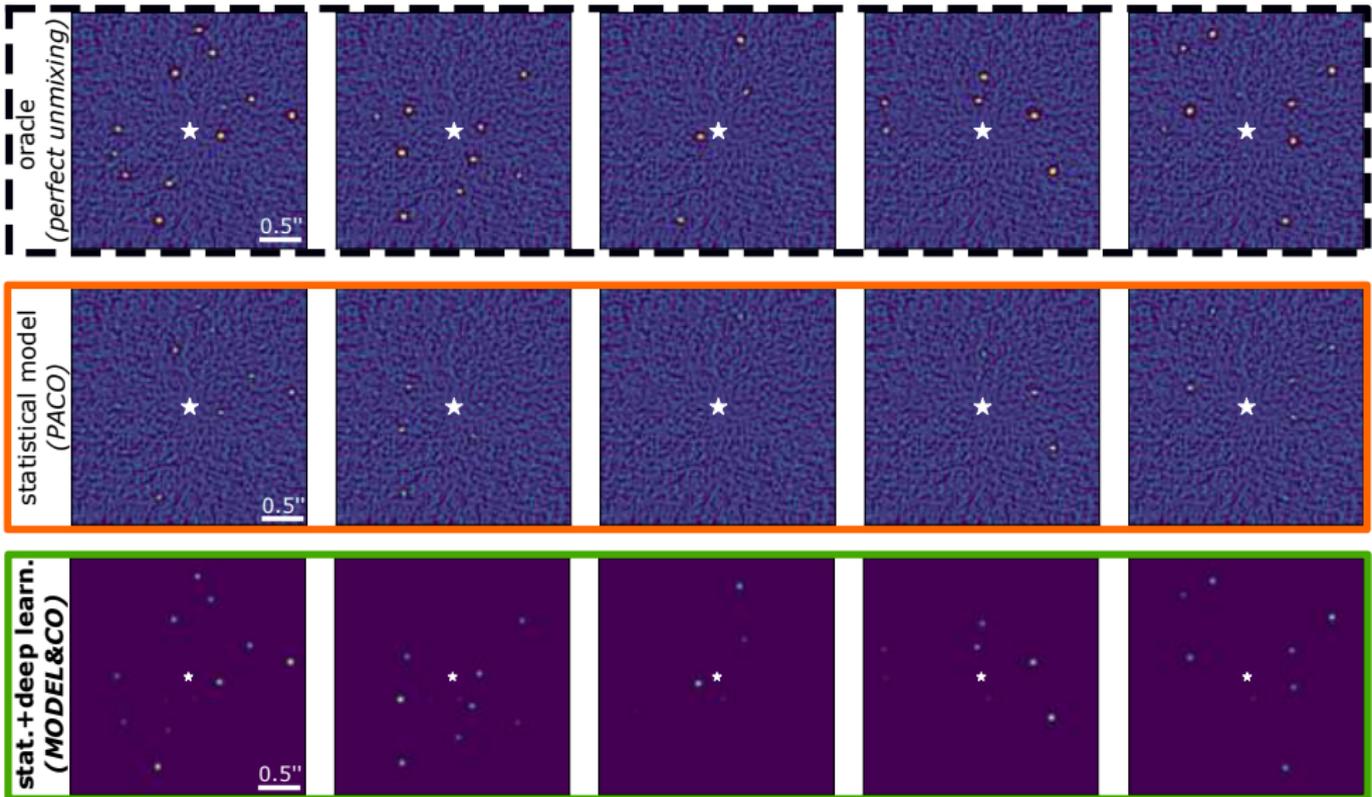
deep models for  
pre-processing  
(speckles aligned)  
AND  
source detection  
(object aligned)

correlations captured  
at a larger spatial scale

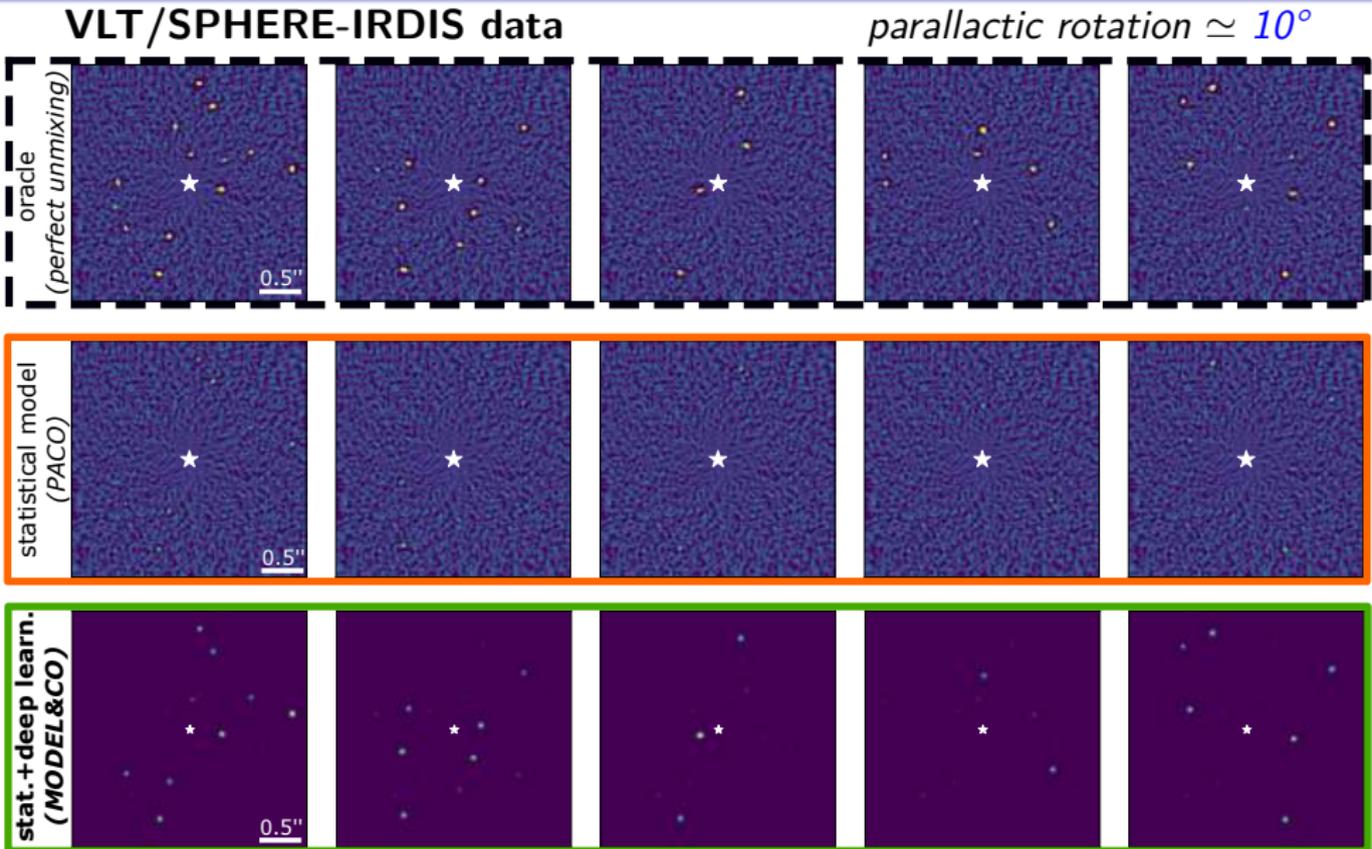
# Results: deep learning by-passes the limits of ADI

VLT/SPHERE-IRDIS data

parallactic rotation  $\approx 23^\circ$



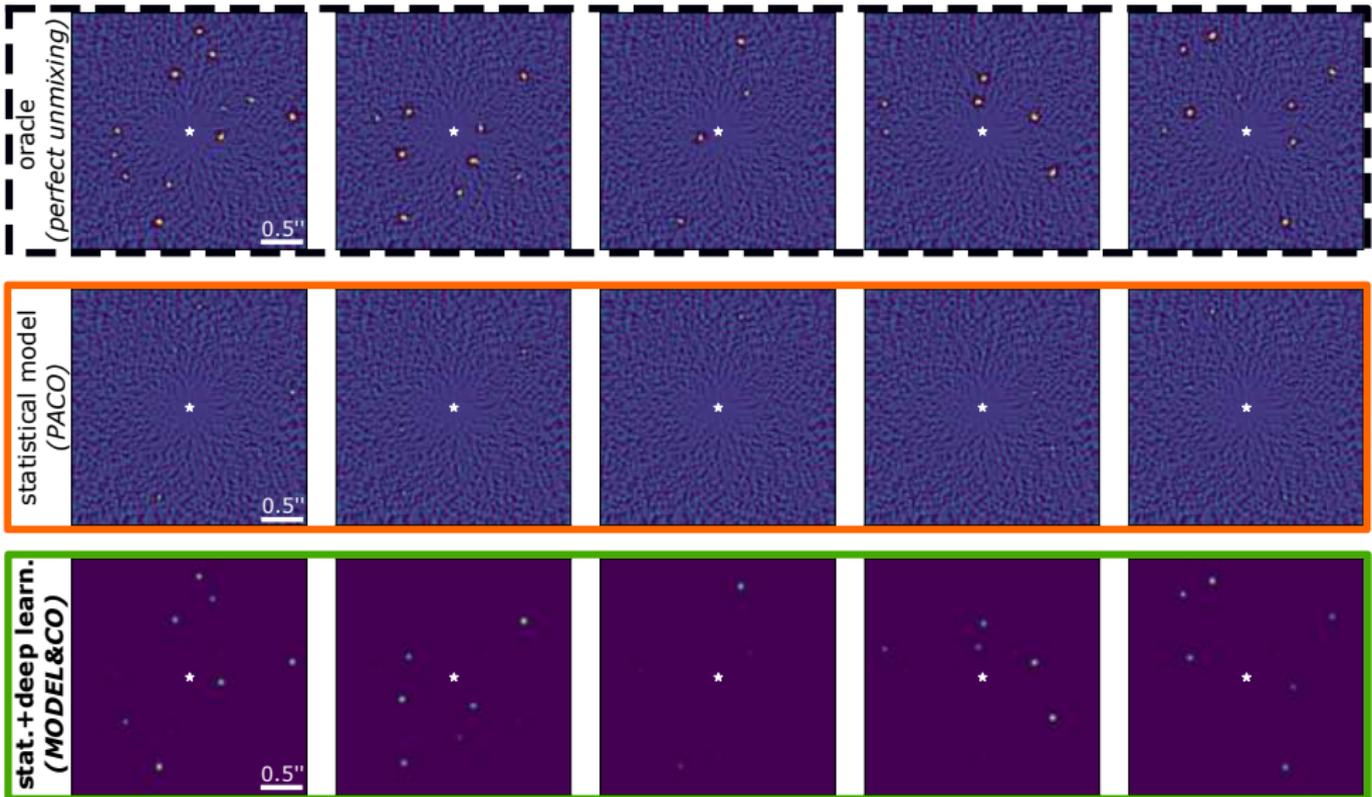
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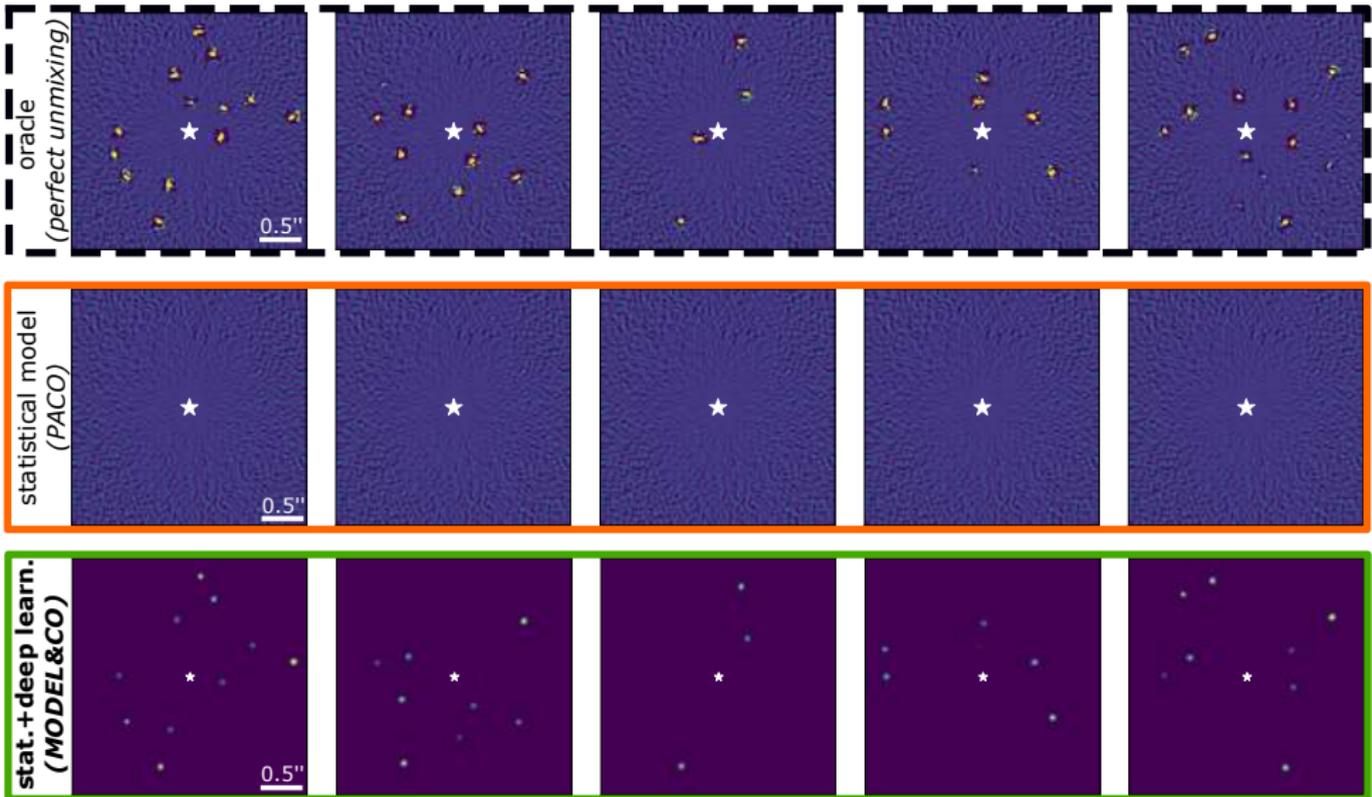
parallactic rotation  $\simeq 6^\circ$



# Results: deep learning by-passes the limits of ADI

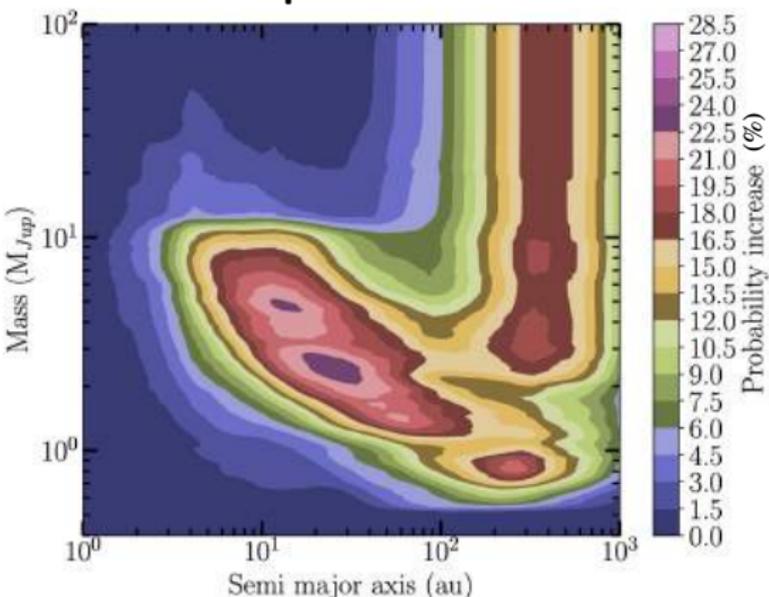
VLT/SPHERE-IRDIS data

*parallactic rotation  $\simeq 2^\circ$*



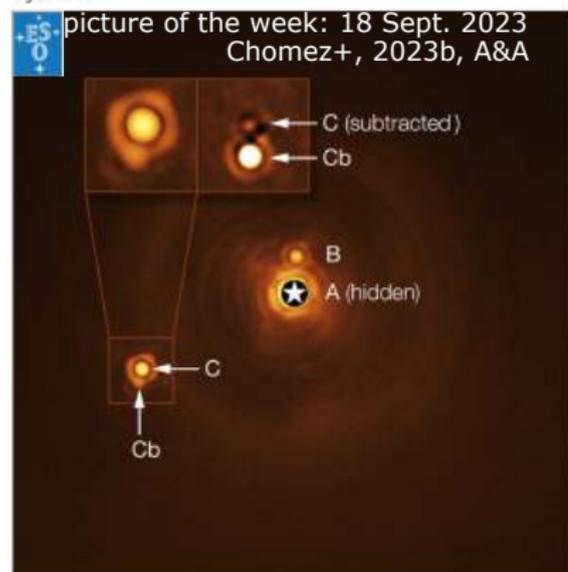
# Progresses in data science $\Rightarrow$ promising results

## Some examples:



Chomez+, to be submitted, 2024

New planetary-mass object found in quadruple system



$\Rightarrow$  **improved completeness on VLT/SPHERE**

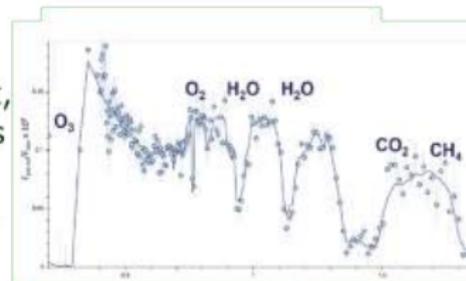
*> 20 candidates to be confirmed with second epoch analysis*

# What's next?

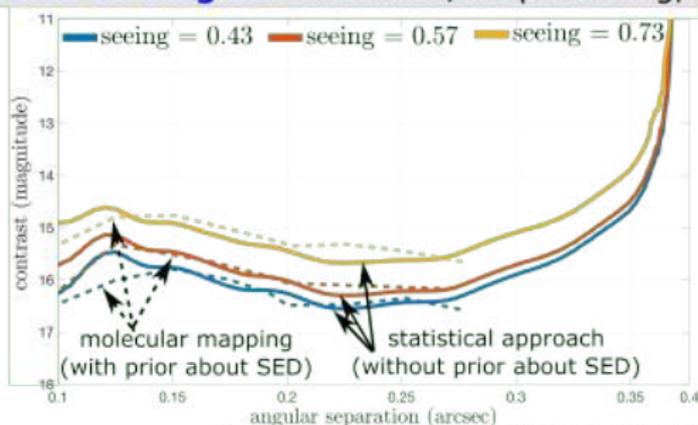


## Goals:

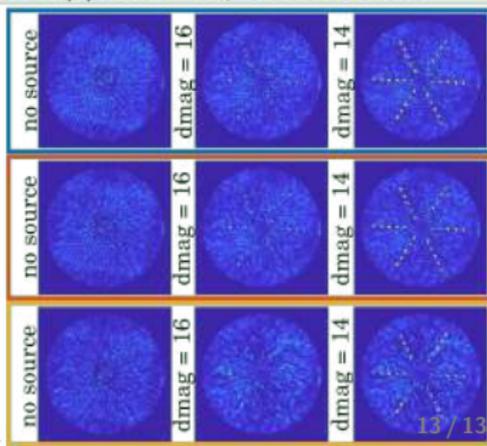
imaging in reflected light,  
Neptune analogs, access  
to telluric...Earth's  
twins...prebiotic signs...



**Data peculiarities:** high spectral diversity, instabilities, highly structured PSF, massive  
**Some strategies:** statistical /deep learning, data-driven approaches, data fusion



Courtesy simulations + photometry code: HARMONI simulation team.

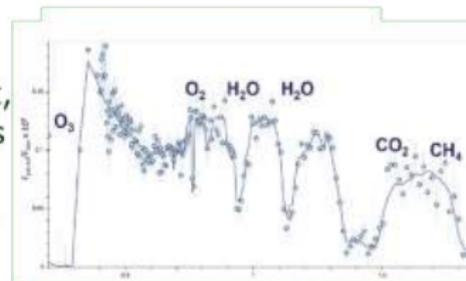


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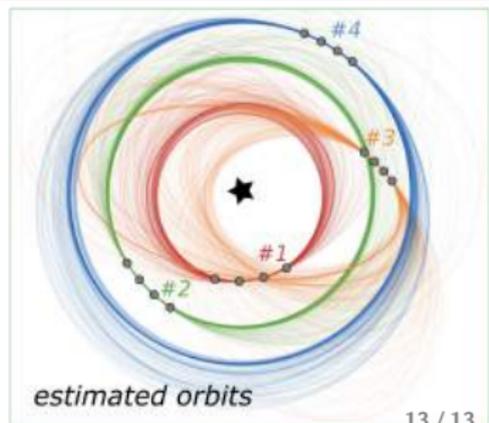
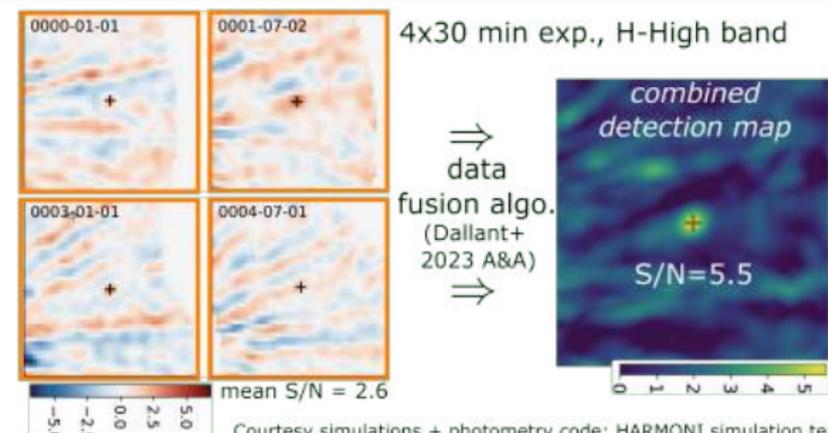


## Goals:

imaging in reflected light,  
Neptune analogs, access  
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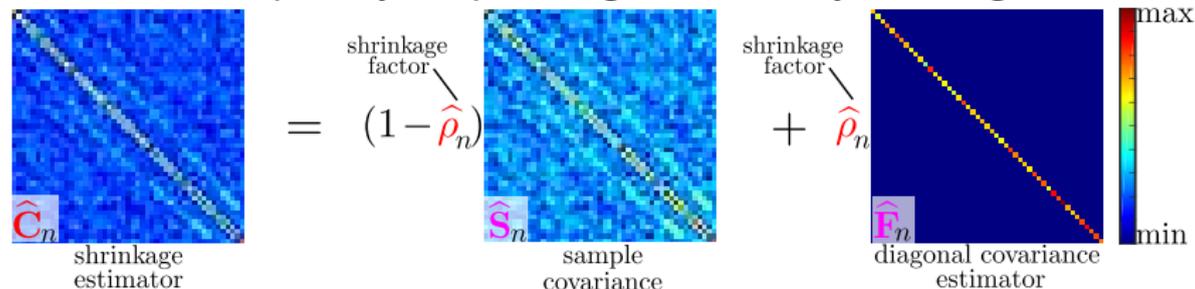


Courtesy simulations + photometry code: HARMONI simulation team.

Thank you

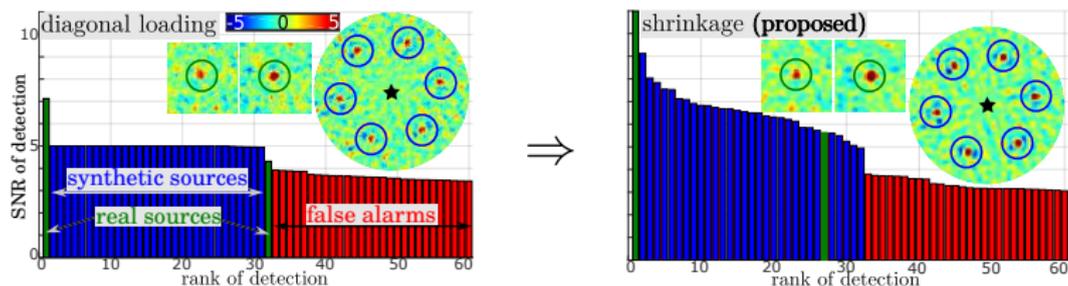
# Accurate estimation in large dimension – *example*

- Low nb of samples ( $T \simeq L \simeq K$ )  $\Rightarrow \hat{\mathbf{S}}_n^{\text{spat}}$  and  $\hat{\mathbf{S}}_n^{\text{spec}}$  noisy/rank-deficient
- Data-driven and spatially adaptive regularization by *shrinkage*:

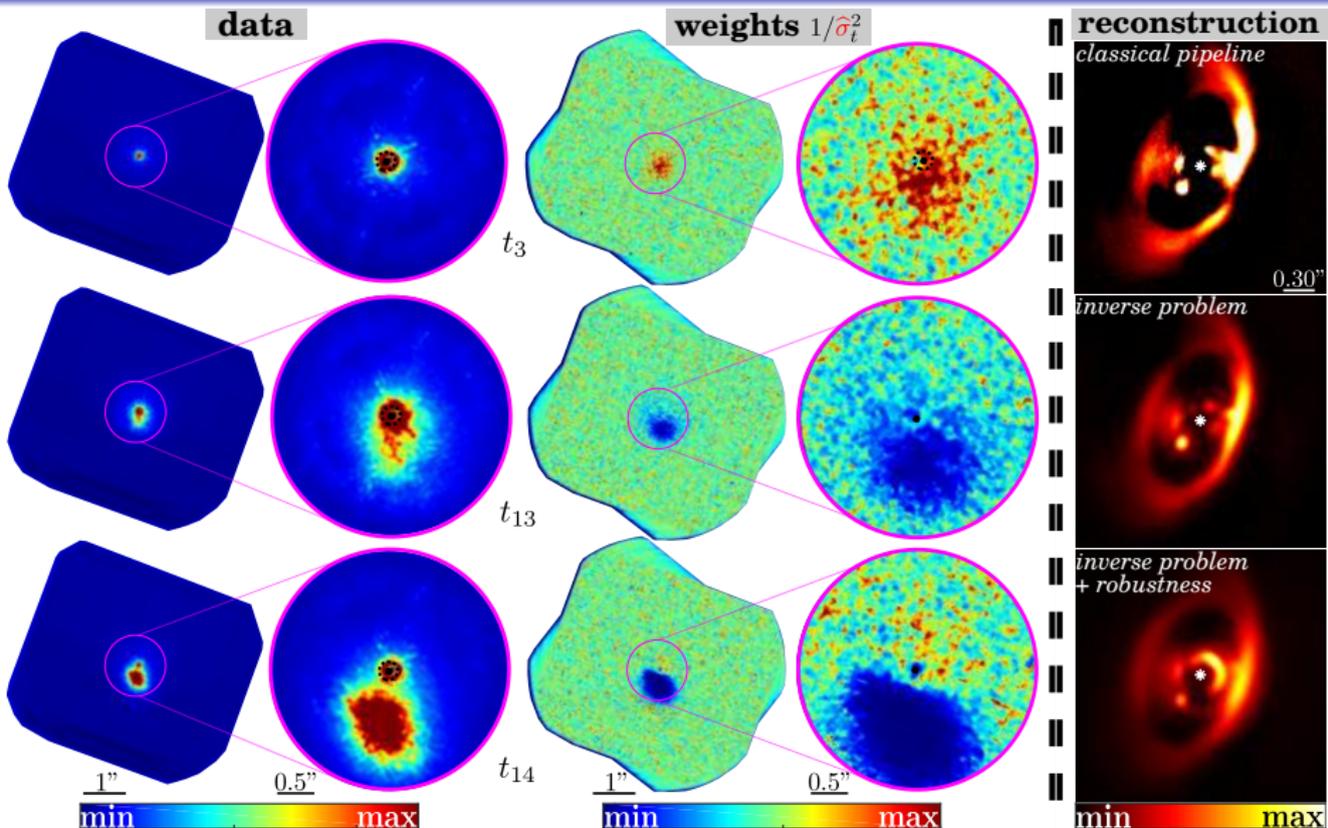


$\Rightarrow$  **optimal estimation by risk minimization for various structures**

$$\hat{\rho}_n = \arg \min_{\rho \in [0,1]} \mathbb{E}(\|\hat{\mathbf{C}} - \mathbf{C}\|_{\text{F}}^2) = \frac{\mathbb{E}(\text{tr}((\mathbf{C} - \gamma \hat{\mathbf{S}})(\hat{\mathbf{F}} - \hat{\mathbf{S}}))}{\gamma \mathbb{E}(\text{tr}((\hat{\mathbf{F}} - \hat{\mathbf{S}})^2))}, \text{ with } \mathbb{E}(\hat{\mathbf{S}}) = \gamma^{-1} \mathbf{C}.$$

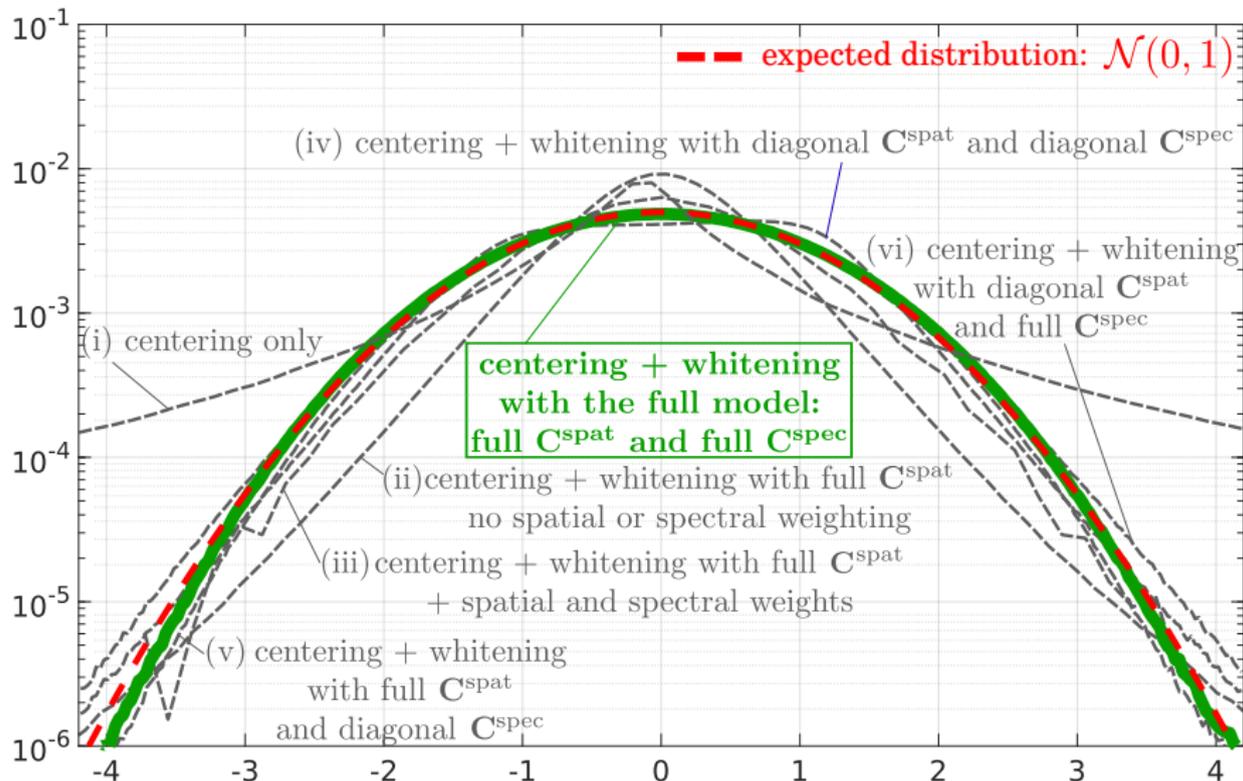


# Accounting for the *variability* of the nuisance component



⇒ large stellar leakages + outliers are identified & neutralized locally

# Model relevance – empirical distribution of residuals



⇒ modeling correlations of the nuisance is critical!

# Unsupervised & optimal setting of the algorithm

## Optimizing a quantitative criterion

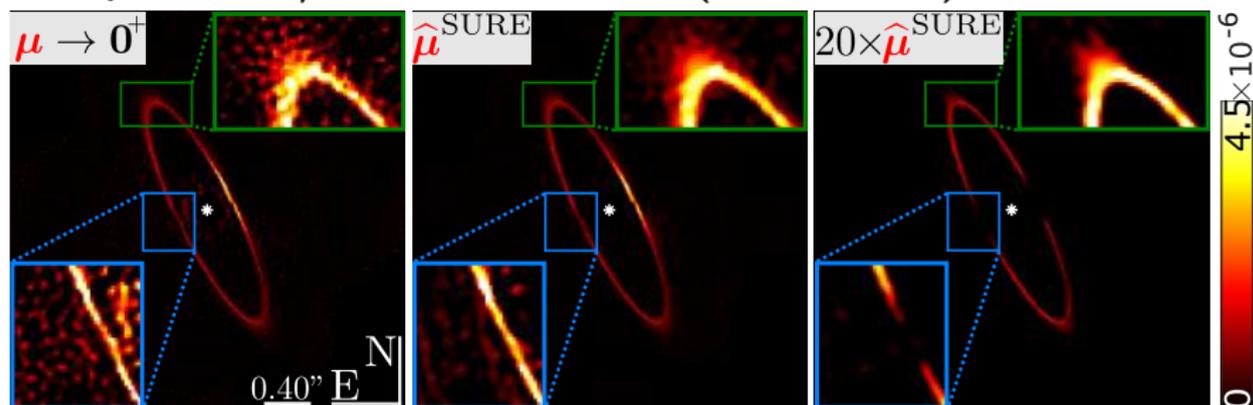
$$\mathcal{R}(\mathbf{x}, \boldsymbol{\mu}) = \underbrace{\mu_{\ell_1}}_{\text{sparsity}} \sum_{n=1}^{N'} \sum_{\ell=1}^L |\mathbf{x}_{n,\ell}| + \underbrace{\mu_{\text{smooth}}}_{\text{smoothness}} \sqrt{\frac{1}{L} \sum_{\ell=1}^L \|\nabla_n \mathbf{x}_{\cdot,\ell}\|_2^2} + \tau^2$$

⇒ **Minimizing e.g. SURE (unbiased MSE estimator):**

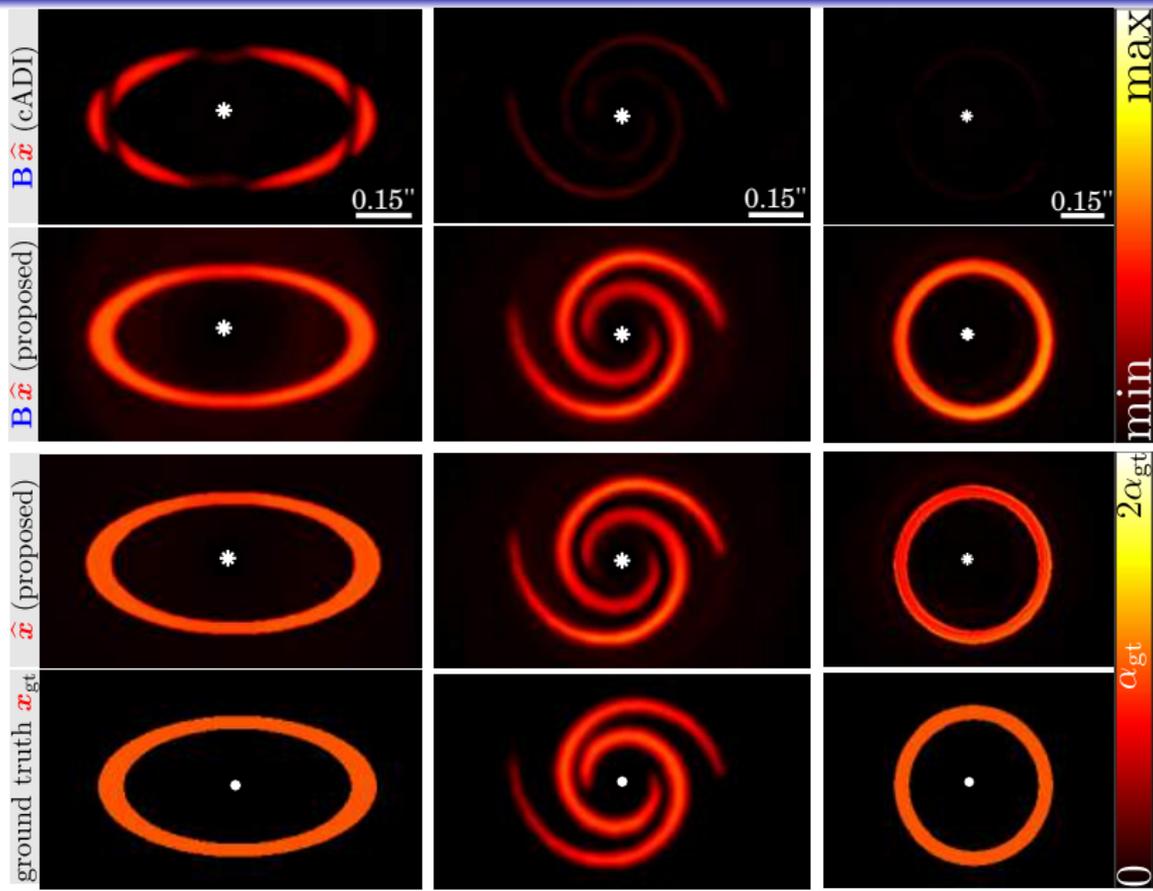
$$\text{SURE}(\boldsymbol{\mu}) = \sum_{n,t} \|\mathbf{r}_{n,t} - \widehat{\mathbf{m}}_n - [\mathbf{A} \mathbf{x}_{\boldsymbol{\mu}}(\mathbf{r})]_{n,t}\|_{\widehat{\sigma}_{n,t}^{-2} \widehat{\mathbf{C}}_{n-1}}^2 + 2 \text{tr}(\mathbf{A} \mathbf{J}_{\mathbf{v}_{\boldsymbol{\mu}}}(\mathbf{r})) - NL$$

**by accounting for the local statistics  $\Omega$  of  $f$ .**

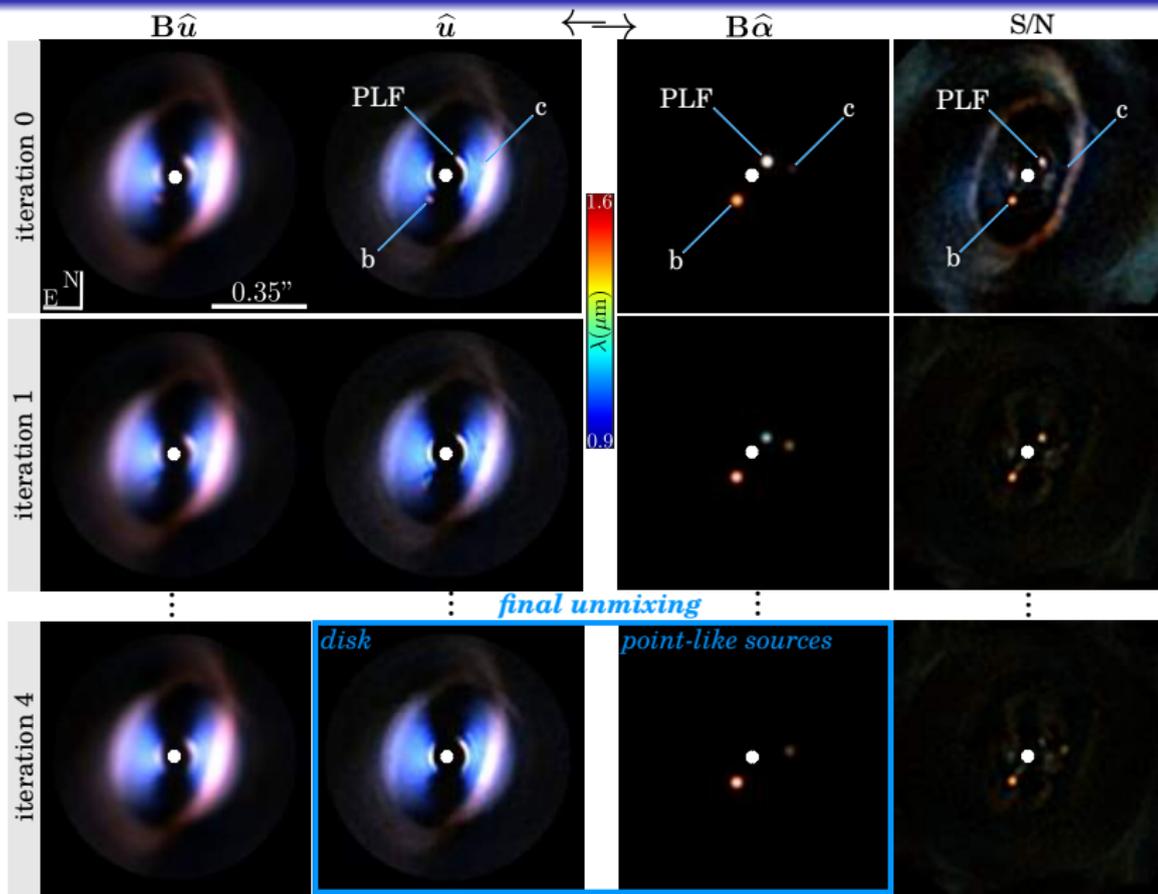
**Example on VLT/SPHERE-IRDIS data (star HR 4786):**



# Results – SPHERE-IFS data with synthetic disks

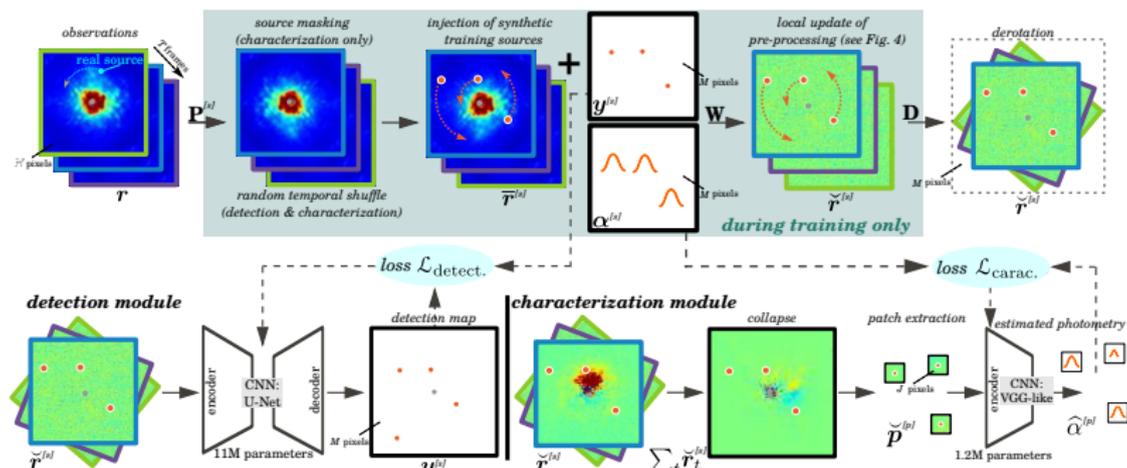


# Unmixing point-like sources and extended features



# Learning pipeline

Tasks: supervised pixel-wise classification, supervised regression.



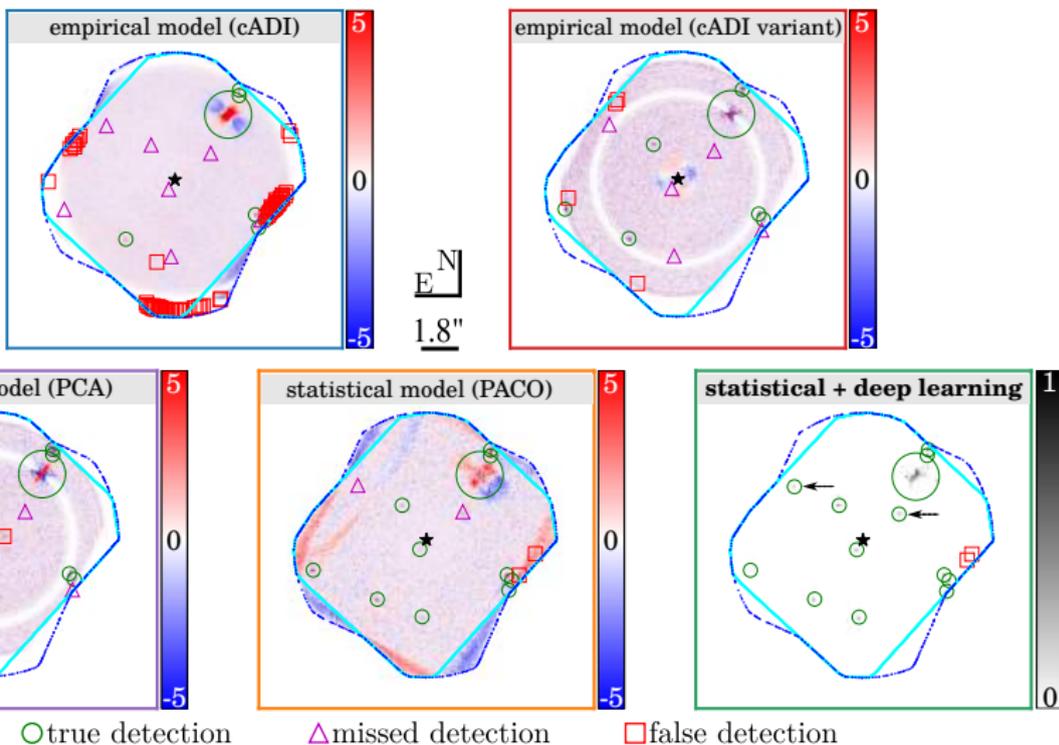
Detection loss: similarity metric for very unbalanced classes.

$$\mathcal{L}(\mathbf{y}^{[s]}, \hat{\mathbf{y}}^{[s]}) = 1 - \underbrace{\frac{\sum_{m=1}^M \mathbf{y}_m^{[s]} \hat{\mathbf{y}}_m^{[s]} + \epsilon}{\sum_{m=1}^M \mathbf{y}_m^{[s]} + \hat{\mathbf{y}}_m^{[s]} + \epsilon}}_{\text{source error}} - \underbrace{\frac{\sum_{m=1}^M (1 - \mathbf{y}_m^{[s]}) (1 - \hat{\mathbf{y}}_m^{[s]}) + \epsilon}{\sum_{m=1}^M 2 - \mathbf{y}_m^{[s]} - \hat{\mathbf{y}}_m^{[s]} + \epsilon}}_{\text{background error}}$$

⇒ **Dedicated data-augmentation + whitening + loss:**  
**deep model specialized for each datacube without overfitting**

# Results: an example of detection maps

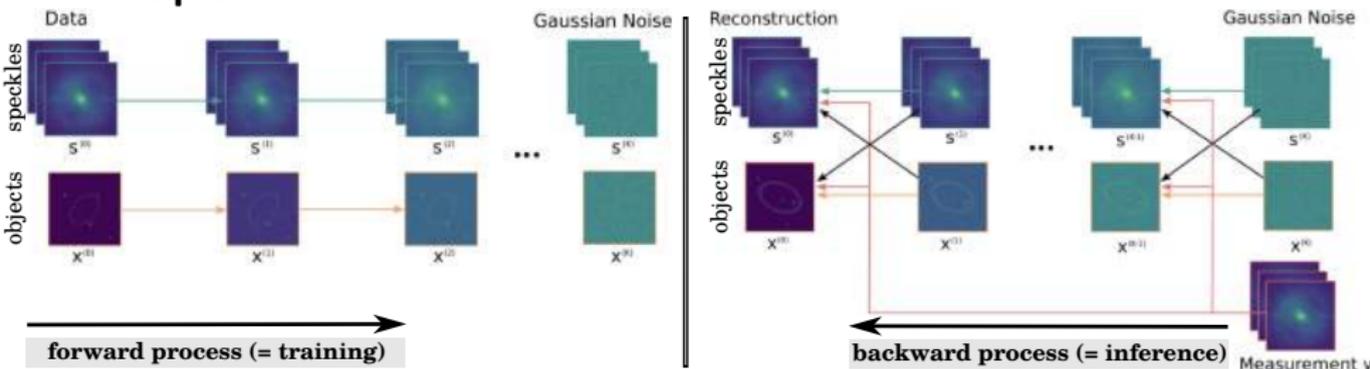
## VLT/SPHERE-IRDIS data (HD 95086)



(Flasseur+ 2023, MNRAS, <https://arxiv.org/abs/2303.02461>)

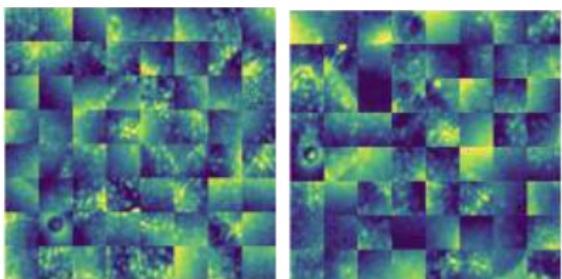
# Generative approach via diffusion model

## Principle:

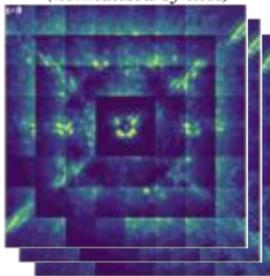


## Results:

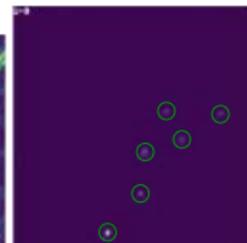
examples of training speckles    examples of generated speckles



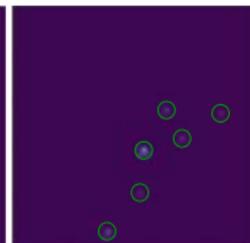
reconstructed speckles  
(normalized by tiles)



reconstructed object



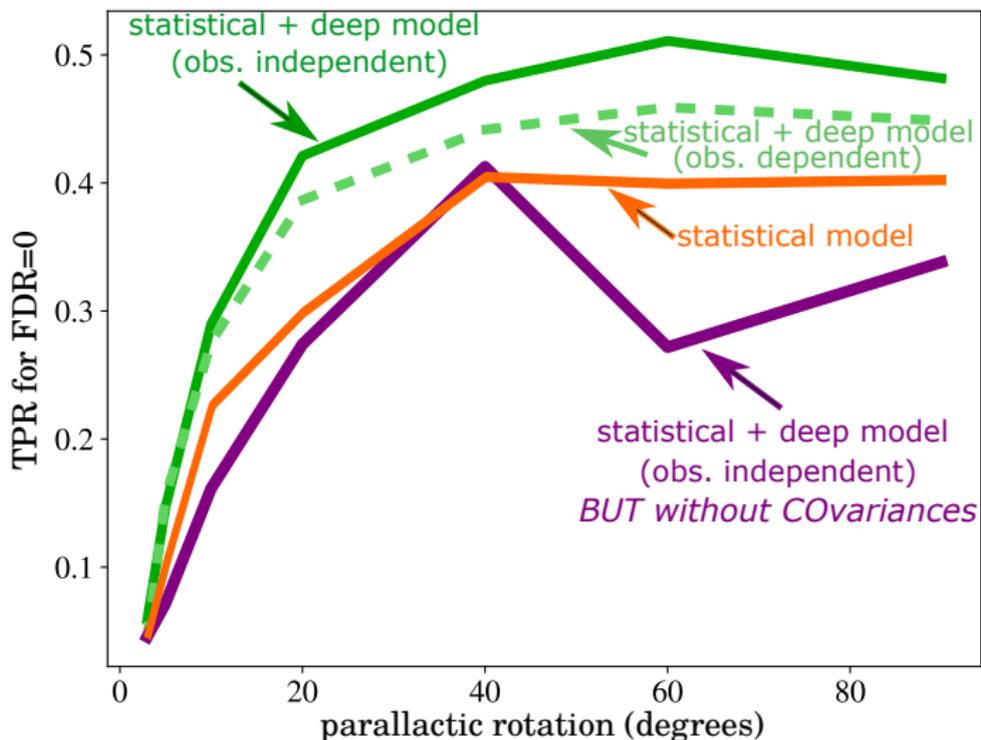
groundtruth object



⇒ Realistic generated speckles but limited detection sensitivity

# Model ablation: importance of statistical model

## ROCs: mean results on VLT/SPHERE-IRDIS data



⇒ **Modeling statistically the covariances is critical!**

# Fusing multiple observations

